

Energy analysis and optimizing of hybrid WT/ PV cell in power systems

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Abstract

The importance placed on renewable energy is growing exponentially due to rising demand for energy, concerns about the environmental impact of burning fossil fuels and fears about the world's limited fossil fuel reserves. This study features an optimal combination of scattered production sources (wind-solar), an IEEE 33-bus system, and beta distribution to model wind speed. The load and production planning period is 24 hours. The aim of this study is to improve voltage profiles, increase reliability and reduce losses. The resulting model forecast a 39% loss-improvement in the presence of wind turbines and a 40% loss-improvement in the presence of photovoltaic cells, which highlights the role of these renewable resources in the grid.

Introduction

Since distribution networks are well-suited for connecting to the power system, the most important step in using Distributed Generation (DG) is to place DG systems in distribution networks and achieve optimal capacity. This is important because it reduces costs associated with casualties, reliability, and the cost of building production units [1–3] and pylons. On the other hand, uncertainty is one of the most important factors increasing risk in the planning of power systems, so failure to consider this parameter can lead to significant economic and technical losses.

Distributed generation sources are now widely used in electrical systems due to their importance in energy production[4,5]. Sincron generators are one of the most common forms of dispersed products installed in medium pressure distribution systems. Because of the

type of synchronous generator, DG performance capabilities, which have different operating modes such as power factor and voltage control, as well as the ability to operate in different locations, can also affect the performance of voltage control and reactive power equipment[6–8]. Therefore, to ensure that ULTC and especially DG do not adjust the appropriate voltage in the system, distribution system units must be connected to the grid in coordination with other equipment of the system [9,10].

Several studies have been proposed on the control of voltage and reactive power in electrical energy distribution systems without examining the effect of DG [11–15]. Given the scope of the problem, most research has sought to achieve the best response in the shortest possible time, with only feeder capacitors being subject to optimal voltage and reactive power control, while low capacitors are not considered [16–18].

In order to solve the multi-objective problem of voltage control and reactive power, the phase building of target and constraint functions as well as the metal hardening algorithm have been used to determine the final answer [19,20]. To reduce the search space, a time-based algorithm was used to predict the 24-hour forecast in order to determine the position of the pulse at any time interval, as well as the genetic algorithm to determine the optimal response [21]. Voltage and reactive power control was conducted in the presence of a scattering source of induction machine (wind turbine) and using a combination of local and centralized control of equipment [21,22]. Feeder

capacitors are controlled by a local voltage type controller: an abnormal position in the controller. The changer's low and high capacitors can be remotely controlled on a daily basis. In both local and proposed controls, DG and the effect of how the change control function has been proposed were investigated. Reactive voltage and power control is performed in the presence of scattered generator-based generator sources, and it is assumed that all equipment has only local control capability.

Meanwhile, assuming that the distribution system is automated, centralized control of control equipment is conducted at any time of the day and night, observing the prevailing restrictions and with objectives such as: reducing losses and improving voltage profiles. This control is done in two modes with and without the presence of a scattered production source and in two modes of power: factor control and voltage control. Also in the considered problem, DG is the effect of location and capacity. Due to the discrete space of the optimization problem, the genetic algorithm was used to optimize and determine the position of the equipment 24 hours a day. Driving a series of developments in transmission and distribution technology have been the design and operation of power systems with maximum efficiency, maximum reliability and safety. This is also the case with reactive power control in transmission and distribution networks. The desired goals are in particular to increase the transmission capacity of existing lines, prevent rapid and large changes in the voltage level, improve the power factor, and balance the load.

Materials and methods

Network Modeling 33-Bus Considering Load Uncertainty and Production

This section reports on the modeling of the 33-bus network in a 24-hour, seasonal manner with uncertainty of load and production. The modeling is tested against a reference. We modeled the 33-bus network with a new arrangement and compared the results for the voltage, loss, and network security profiles with a previous 33-bus distribution network layout, to see the effect of the new layout on the network's basic parameters and in real time. Full

information will be provided regarding the IEEE 33-bus standard standard network. The network is shown schematically in 1.

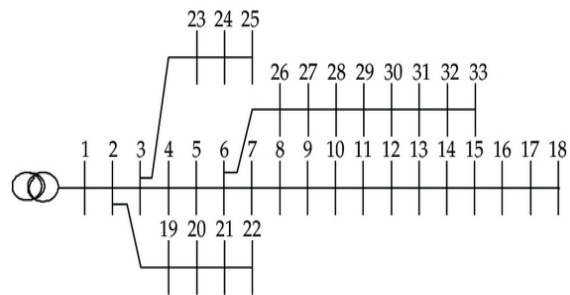


Figure 1. Schematic diagram of IEEE 33-bus bar network

As you can see from 1 the 33-bus network consists of four main branches that are connected to the transmission network via a 1-bus and a transformer. Information about this network, including the maximum active and reactive power of the network, the resistance value and the reactance of the lines, is given in 1 and 2.

Solar and wind

2 shows the hourly generation using wind and solar sources. The figure on the right shows wind and on the left sun. In addition to being hourly, the production rate is also shown seasonally. Weibull distribution is used for wind and beta distribution for solar.

Electrical load

The following figure shows power consumption per hour for different seasons. To show the uncertainty of the load, load planning was considered as 24-hour and seasonal. That way, we can bring the simulation results closer to reality, with the possibility of load and production.



Table 1: Maximum amount of active and reactive power of 33-bus network

Bus number	2	3	4	5	6	7	8	9
P_L (kW)	100	90	120	60	60	200	200	60
q_L (Kvar)	60	40	80	30	20	10	10	20
Bus number	10	11	12	13	14	15	16	17
P_L (kW)	60	45	60	60	120	60	60	60
q_L (Kvar)	20	30	35	35	80	10	20	20
Bus number	18	19	20	21	22	23	24	25
P_L (kW)	90	90	90	90	90	90	420	420
q_L (Kvar)	40	40	40	40	40	50	200	200
Bus number	26	27	28	29	30	31	32	33
P_L (kW)	60	60	60	120	200	1505	210	60
q_L (Kvar)	25	25	20	10	60	70	10	40

Table 2. Resistance and reactance values of 33-bus network lines

Line number	1-2	2-3	3-4	4-5	5-6	6-7	7-8	8-9
r_k	0.0922	0.4930	0.3660	0.3811	0.8190	0.1872	0.711	1.030
X_k	0.0470	0.2511	0.1846	0.1941	0.7070	0.6188	0.235	0.740
Bus number	9-10	10-11	11-12	12-13	13-14	14-15	15-16	16-17
r_k	1.04	0.19	0.37	1.46	0.54	0.59	0.74	1.28
X_k	0.74	0.06	0.12	1.15	0.71	0.52	0.54	1.72
Bus number	17-18	18-19	19-20	20-21	21-22	22-23	23-24	24-25
r_k	0.73	0.16	1.50	0.40	0.70	0.45	0.89	0.89
X_k	0.57	0.15	1.35	0.47	0.93	0.30	0.70	0.70
Bus number	6-27	26-27	27-28	28-29	29-30	30-31	31-32	32-33
r_k	0.20	0.28	1.05	0.80	0.50	0.97	0.31	0.34
X_k	0.10	0.14	0.93	0.70	0.25	0.96	0.36	0.53

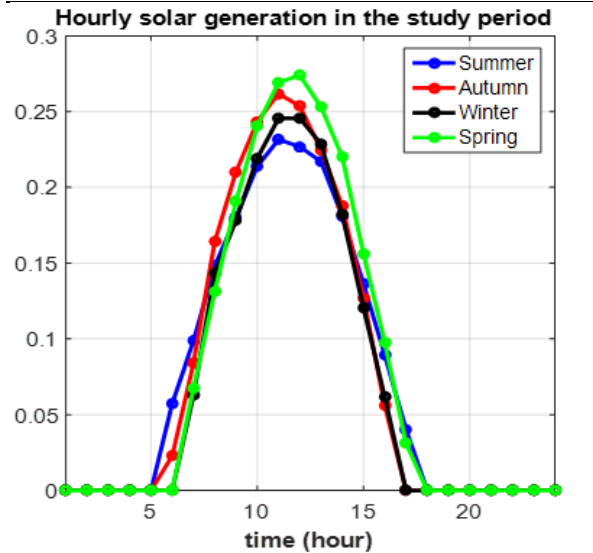
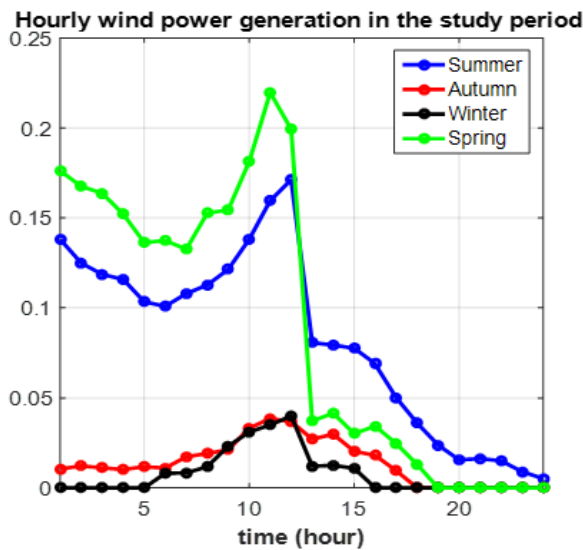


Figure 3. Power consumption per hour

Possible power generation model

Wind and solar generation is affected by weather conditions such as sunlight, wind speed and ambient temperature. Probability distribution functions (PDFs) can be used in a statistical manner to identify the random behavior of a renewable source (wind speed and solar radiation). The probability of solar radiation was considered following the Beta PDF. The beta distribution of solar radiation (kw/m^2) s^t during the time segment t' is as follows[20].

$$f_s^t(s) = \frac{\Gamma(\alpha^t + \beta^t)}{\Gamma(\alpha^t) \cdot \Gamma(\beta^t)} \cdot (s^t)^{\alpha^t - 1} \cdot (1 - s^t)^{\beta^t - 1} \text{ for } \alpha^t > 0; \beta^t > 0 \quad (1)$$



Here β^t & α^t are parameter forms in t , and Γ also indicates the gamma function. The shape of the Beta PDF parameters can be calculated using the mean (μ_s^t) and standard deviation (σ_s^t) of radiation for the relevant time segment.

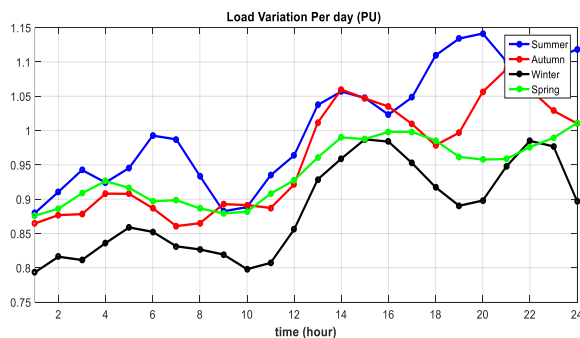
$$\beta^t = (1 - \mu_s^t) \cdot \left(\frac{\mu_s^t(1 + \mu_s^t)}{(\sigma_s^t)^2} - 1 \right) \quad (2)$$

$$\alpha^t = \frac{\mu_s^t * \beta^t}{(1 - \mu_s^t)} \quad (3)$$

Figure 2. Wind and solar production per hour

The decision to describe the random behavior of wind speeds is selected in a predetermined period of time Weibull PDF. The distribution of Weibull for wind speed V^t (m/s) in the time interval tm can be expressed as follows [23,24]

$$f_v^t(v) = \frac{k^t}{c^t} \cdot \left(\frac{v^t}{c^t} \right)^{k^t - 1} \cdot \exp\left(-\left(\frac{v^t}{c^t}\right)^{k^t - 1}\right) \text{ for } c^t > 1; k^t > 0 \quad (4)$$



The parameter (k^t) and the scale factor (c^t) in the time segment tm are calculated as follows:

$$k^t = \left(\frac{\sigma_v^t}{\mu_v^t} \right)^{-1.086} \quad (5)$$



$$c^t = \frac{\mu_v^t}{\Gamma(1 + 1/k^t)} \quad (6)$$

μ_v^t And σ_v^t are the mean standard wind deflection deviations in time segment t. To calculate the output power of wind and solar DGs, continuous PDFs are divided into periods for a specific time frame. In each of them, solar radiation and wind speed are at a certain level. Production of Pv and WT array power is controlled by the probability of all possible states for that time.

The average hourly output power of a PV array is related to a specific time segment $t(P_{pv}^t)$ which can be calculated as follows: [23].

$$P_{pv}^t = \sum_{g=1}^{N_s} PG_{PVg} * P_s(s_g^t) \quad (7)$$

Here g determines the variable of state (period) and N_s the number of discrete states of solar radiation. S_g^t is also g a_{min} state / solar radiation level in t a_{min} time fragment. The probability of solar radiation for each state for each specific time frame is calculated as follows:[24]

$$P_s(s_g^t) = \begin{cases} \int_0^{(s_g^t+s_{g+1}^t)/2} f_s^t(s)ds & \text{for } g = 1 \\ \int_{(s_{g-1}^t+s_g^t)/2}^{(s_g^t+s_{g+1}^t)/2} f_s^t(s)ds & \text{for } g = 2 \dots (N_s - 1) \\ \int_{(v_{s-1}^t+v_s^t)/2}^{\infty} f_s^t(s)ds & \text{for } g = N_s \end{cases} \quad (8)$$

Sunlight and ambient temperature are the main factors influencing the output power of the Pv array. The power output of the Pv array in average solar radiation (sag) for g a_{min} state / level is evaluated as follows. [23]

$$PG_{PVg}(s_{ag}) = N_{PVmod} * FF * V_g * I_g \quad (9)$$

Here N_{pvmod} is the sum of the number of Pv modules used for a Pv array. The current-voltage characteristic of the Pv module can be determined for a specific radiation level and ambient temperature T_A (°C) using the following equations [23,24]

$$I_g = s_{ag}[I_{SC} + K_i(T_C - 25)] \quad (10)$$

$$V_g = V_{OC} - K_v * T_{cg} \quad (11)$$

$$T_{cg} = T_A + s_{ag} \left(\frac{N_{OT} - 20}{0.8} \right) \quad (12)$$

$$FF = \frac{V_{MPP} * I_{MPP}}{V_{OC} * I_{SC}} \quad (13)$$

T_{cg} temperature of the solute in g Amin is the state of k_v and k_i ; (°C) is the coefficient of current and voltage temperature (A/ °C and V/ °C); N_{OT} is the nominal operating temperature of the cell; FF (°C) is the filling factor; V_{OC} and I_{SC} are open circuit voltage (V) and the short circuit current (A) I_{MPP} and V_{MPP} are also the voltage (V) and current (A) at the maximum power point, respectively.

$$P_{WT}^t = \sum_{g=1}^{N_v} PG_{WTg} * P_v(v_g^t) \quad (14)$$

The probability of wind speed for each mode during each specific time frame is calculated as follows:[20]

$$P_v(v_g^t) = \begin{cases} \int_0^{(v_g^t+v_{g+1}^t)/2} f_v^t(v)dv & \text{for } g = 1 \\ \int_{(v_{g-1}^t+v_g^t)/2}^{(v_g^t+v_{g+1}^t)/2} f_v^t(v)dv & \text{for } g = 2 \dots (N_v - 1) \\ \int_{(v_{g-1}^t+v_g^t)/2}^{\infty} f_v^t(v)dv & \text{for } g = N_v \end{cases} \quad (15)$$

WT power generation depends on its power performance curve. For nonlinear performance characteristics, the production of WT power at average wind speed (V_{ag}) for mode (g) is calculated as follows.

$$PG_{WTg} = \begin{cases} 0 & v_{ag} < v_{cin} \text{ OR } v_{ag} > v_{cout} \\ (a * v_{ag}^3 + b * P_{rated}) & v_{cin} \leq v_{ag} \leq v_N \\ P_{rated} & v_N \leq v_{ag} \leq v_{cout} \end{cases} \quad (16)$$

Here P_{rated} is the maximum power that can be generated through WT. v_{cout} The wind speed is maximum. Fixes a and b are a function of the minimum wind speed v_{cin} and the nominal wind speed (v_N), which are calculated as follows:

$$a = \frac{P_{rated}}{(v_N^3 - v_{cin}^3)} \quad (17)$$

$$b = \frac{V_{cin}^3}{(V_N^3 - V_{cin}^3)} \quad (18)$$

Since DG distribution networks are active networks, performance and control of the network are key issues. Although there are a number of issues with the distribution network's performance, there are also major technical implications due to the influence of renewable DGs, such as network power loss, voltage stability, and network security discussed here.

Distribution networks are usually radially structured to reduce the complexity of protection. Assessing and reducing network power losses is essential to increase system efficiency. The average power loss per year can be calculated as follows:

$$Ploss_a = \frac{\sum_{t=1}^{N_t} \sum_{i=1}^{N_b} r_i ((P_{D,i+1}^t)^2 + (Q_{D,i+1}^t)^2)}{N_t (V_{i+1}^t)^2} \quad (19)$$

Here $Q_{(D,i+1)}^t$ and $P_{(D,i+1)}^t$ are the demand for active and reactive power in the receiver end bus $-i + 1$ for t amen. $V_{(i+1)}^t$ The amplitude of the voltage at the end bus receiving the $-i + 1$ for t is the time interval. r_i The resistance of the completed transmission line to bus N_i , $-i + 1$ is the sum of the number of lines in the system and N_t is the sum of the number of time pieces considered in a year.

Voltage stability indicators are used to assess the level of voltage stability of buses in the transmission or distribution network. These are very fast and effective tools for calculating the offline stability of voltage buses. The voltage stability index VSF (Voltage Stability Factor) for each bus $-i + 1$ in time interval t can be expressed as follows.

$$VSF_{i+1}^t = (2V_{i+1}^t - V_i^t) \quad (20)$$

The average annual voltage stability for the entire distribution network can be calculated as follows:

$$VSF_a = \frac{\sum_{t=1}^{N_t} \sum_{i=2}^{N_b} VSF_{i+1}^t}{N_t(N_b - 1)} \quad (21)$$

N_b is the sum of the number of buses in the network. The bus $-i + 1$ is assumed to be in the main distribution post. The researchers looked at how high the VSF was. The network is more stable. If the line capacity increases from the existing transmission capacity, it will be overloaded, which is likely to cause network

congestion, which in turn will cause various types of network disruptions. Line load (LL) is the load distribution (MVA) on the line according to the maximum power capacity (MVA), which is expressed for line i during time interval " t " as follows:

$$LL_i^t = \frac{L_{MVA,i}^t}{L_{MVA,max,i}} \quad (22)$$

Here $L_{MVA,max,i}^t$ and $L_{MVA,i}^t$ is the real capacity and maximum line i in t is the time interval. The annual average network security index (NSI) is plotted according to the loading of all lines in the network, which is as follows:

$$NSI_a = \frac{\sum_{t=1}^{N_t} \sum_{i=1}^{N_i} LL_i^t}{N_t * N_i} \quad (23)$$

Lower NSI values indicate a lower power risk than lines, which in turn increases network security. The proposed planning method should provide the equality and inequality constraints described below.

$$PG = \sum_{i=2}^{N_b} Pd.i - Ploss = 0 \quad (24)$$

$$QG_{ss} - \sum_{i=2}^{N_b} Qd.i - Qloss = 0 \quad (25)$$

PG_{ss}^t and QG_{ss}^t The active and reactive power fed by mail in t is the timepiece. Lo $Qloss$. $Qloss^t$ And $Ploss^t$ T are the loss of active and reactive power in t is the time frame.

$$V_i^t \leq V_{max,i} \quad (26)$$

V_i^t and $V_{max,i}$ are the actual and maximum voltages in bus i for time interval t .

$$L_{MVA,i}^t \leq L_{MVA,max,i} \quad (27)$$

$L_{MVA,max,i}^t$ and $L_{MVA,i}^t$ are the maximum and actual loads of line i in time interval t .

Photovoltaic cell and wind turbine

The renewable energy sources used in this system are PV cells and wind turbines. The specifications of the wind turbine and PV cell can be seen in 3 and 4.

Table 3. PV module specifications

Parameter	Unit	Amount
Voltage at the maximum point of VMPP power	V	28.36
Flow at the maximum IMPP power point	A	7.76
Open circuit voltage Voc	V	36.96
Short circuit current	A	8.38
Nominal operating cell temperature NOT	°C	43
Thermal flow	A/°C	0.00545
Thermal voltage	V/°C	0.1278

Table 4. Wind turbine specifications

Parameter	Unit	Amount
Permitted nominal output power Prated	kW	250
Internal cutting speed V_{cin}	m/s	3
Nominal wind speed V_N	m/s	12
External cutting speed V_{cout}	m/s	25

As can be seen from Table 3, the maximum power output for the PV cell is 220 W. As can be seen from Table 4, the maximum power output of the wind turbine is 250 kW, this production capacity is possible for wind speeds of 12 m/s or more, the cutting speed for the turbine is 25 m/s.

Results

Results with scattered production sources

Figure 4 shows the amount of electricity generated by the wind turbine and PV cell regardless of the grid. Figure 5 shows the amount of electricity generated by the wind turbine and the PV cell, taking into account the grid mentioned in the previous section.

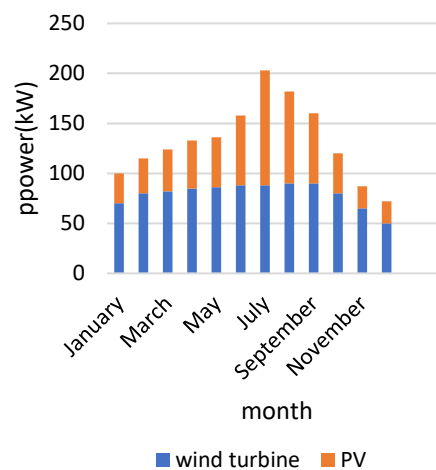


Figure 4. Wind turbine and PV generation without grid

As can be seen in Figure 4, the PV cell outperforms the wind turbine only in July. The wind turbine's highest and lowest electrical production figures are in August and December respectively. For August electrical production is 90 kW/day and for December 50 kW/day. The PV cell's highest and lowest electrical production figures are in July and December: 118 and 22 kW/day, respectively.

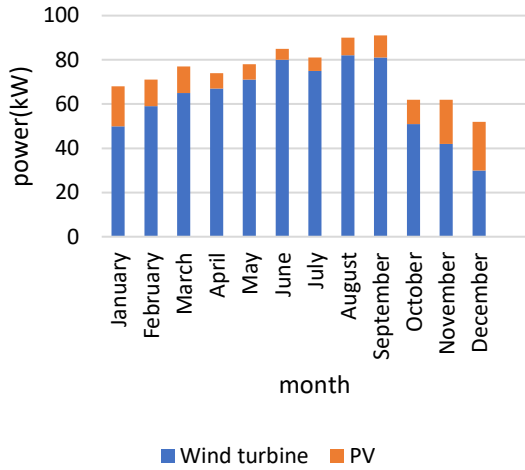


Figure 5. Wind turbine and PV generation with grid

As shown in Figure 5, the highest and lowest electrical production of the renewable energy system are in September and December. For September electrical production is 91 kW/day and for December 50 kW/day. In September, the wind turbine produces 81 kW/day and the PV cell 10 kW/day. In December, the wind turbine produces 30 kW/day and the PV cell 22 kW/day.

The problem is solved as a multi-objective task, and the results show that the system parameters have been improved in multi-objective mode. The following tables show the parameters used for simulation. Figure 6 shows the value of the objective function in different iterations and how to achieve the optimal answer in different iterations. As can be seen, the algorithm reached the optimal answer after 8 repetitions.

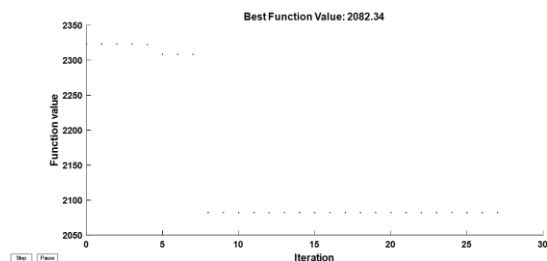


Figure 6. The optimal answer of the algorithm for different iterations

Table 5 shows the simulation results in the first scenario as a single goal and in the second scenario as

a multi-objective. As can be seen, voltage stability in both scenarios is almost equal, but the system security index and multi-objective loss improvements have improved compared to single-target mode.

Table 5. Simulation results for 33-bus system with uncertainty

	Security Index	Voltage Profile	Losses	Location of scattered products
Primary system	0.59	0.91	0.89	—
WT	0.386	0.9288	0.3929	2 5 4 4
PV	0.3772	0.9228	0.4065	5 4 4 4
Optimal (Scenario 1)	0.386	0.9288	0.3922	27 17 13 11
Optimal (Scenario 2)	0.3331	0.919	0.3388	17 9 8 7

Figure 7 shows the multi-objective optical beam curve. As can be seen, the front beam provides a set of answers for the objective functions.

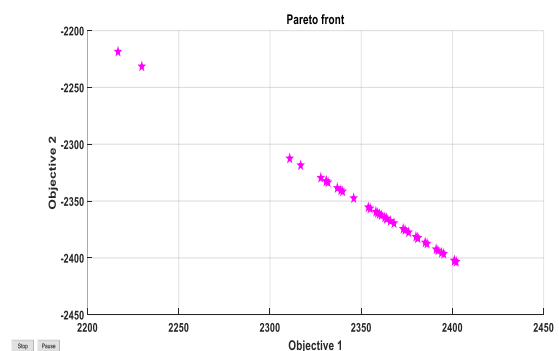


Figure 7. Front beam curve related to multi – objective optimization

Figure 8 shows the amount of electrical power generated by the wind turbine and the PV cell, taking into account the limitations, including optimization.

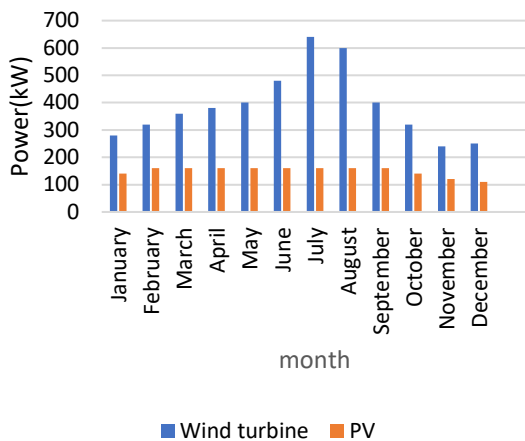


Figure 8. Optimal Wind turbine and PV generation with grid

In Figure 8, the wind turbine's highest power generation is in July, with 640 kW/day. PV production in July is 160 kW/day. The wind turbine's lowest power generation is in November, with 240 kW/day. PV production in November is 120 kW/day. The highest and lowest power generation months for wind turbines and PV cells combined are July and

November. The total electricity produced for July and November is 800 and 360 kW/day, respectively.

Conclusion

Renewable energy sources have attracted a great deal of attention due to their virtually emissions-free operation. Recently, a significant number of distributed generation products (DGs) with intermittent production patterns have connected to the distribution network. Integrating renewable DGs into distribution networks is essential to ensure security of supply and good quality of electricity in the network. This paper presents a simple and effective method for sizing and optimizing the placement of wind and solar DGs in distribution locations, with a view to minimizing the loss of network power, and improving voltage stability and network security. Sunlight and wind speeds were also considered using appropriate models. Weighted particle optimization with weight accumulation was also used to optimize target functions in which the bus voltage limit, line loading capacity, discrete size limit and DG penetration limits are considered.

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